Shack–Hartmann sensor improvement using optical binning

Alastair Basden,* Deli Geng, Dani Guzman, Tim Morris, Richard Myers, and Chris Saunter
Department of Physics, South Road, Durham, DH1 3LE, UK
*Corresponding author: a.g.basden@durham.ac.uk

Received 25 May 2007; accepted 6 July 2007; posted 10 July 2007 (Doc. ID 83374); published 14 August 2007

We present a design improvement for a recently proposed type of Shack–Hartmann wavefront sensor that uses a cylindrical (lenticular) lenslet array. The improved sensor design uses optical binning and requires significantly fewer detector pixels than the corresponding conventional or cylindrical Shack–Hartmann sensor, and so detector readout noise causes less signal degradation. Additionally, detector readout time is significantly reduced, which reduces the latency for closed loop systems and data processing requirements. We provide simple analytical noise considerations and Monte Carlo simulations, we show that the optically binned Shack–Hartmann sensor can offer better performance than the conventional counterpart in most practical situations, and our design is particularly suited for use with astronomical adaptive optics systems. © 2007 Optical Society of America

OCIS codes: 010.1080, 010.7350.

1. Introduction
A conventional Shack–Hartmann sensor (SHS) divides a pupil into subapertures using a lenslet array and attempts to measure the wavefront gradients in orthogonal directions across each subaperture as shown in Fig. 1. Estimation of the wavefront gradients typically involves finding the center of mass of the image spot created in the subaperture (the mean light position). This is typically done by software binning of the measured light signal in one direction when computing the algorithm and then computing the dot product of this vector with an index vector (i.e., a vector counting from 0 to \(N-1\), where \(N\) is the number of pixels in a subaperture). Computation of the corresponding orthogonal wavefront tilt is carried out by software binning the measured light signal in the orthogonal direction. Once these spot centroid locations have been retrieved, a reconstruction algorithm is used to provide an estimate of the wavefront under investigation.

Here, we present a modified version of the SHS described by Ares et al. [1]. This design uses the cylindrical lenslet array proposed previously and also implements optical signal binning. There are a number of situations where this can give a performance improvement when compared with a conventional SHS, which we describe in Section 2. The original cylindrical Shack–Hartmann sensor design described by Ares [1] was intended to provide a reliable way to measure wavefront gradients outside the nominal Shack–Hartmann lenslet area on the detector, such as when there are highly aberrated wavefronts or abrupt phase changes, for time-static aberrations. The design proposed here has an additional aim, to achieve higher wavefront sensor (WFS) frame rates than would be possible using a conventional SHS, by using fewer detector pixels, and also to give improved signal-to-noise ratio (SNR) performance.

A simplified schematic of an optically binned SHS (OBSHS) is given in Fig. 2, along with an example for the detector images. The wavefront is first split with a 50/50 beam splitter. Each of the resulting beams then passes through one of two identical cylindrical (lenticular) lenslet arrays oriented orthogonally, some cylindrical reimaging optics (not shown here for clarity; see Fig. 3), and onto separate detectors. A conventional (circular) lenslet array focuses the wavefront in two directions, giving a conventional point-spread function. Conversely, the cylindrical lenslet arrays proposed here focus the wavefront in...
only one direction. Rather than a single spot, light will be spread along a number of lines as shown in Fig. 2.

The two orthogonal lenslet arrays are required to measure orthogonal wavefront gradients. The design described by Ares [1] used a single cylindrical array that was rotated by 90° to measure the orthogonal wavefront gradients, rather than the beam splitter shown here. A drawback of this technique is that it is only suitable for characterizing static aberrations, as detector images have to be captured before and after the precise 90° rotation.

In order to minimize the number of detector pixels required for wavefront gradient estimation, the OBSHS should be designed such that the width of the focused line [Figs. 2(b) and 2(c)] is \( n_s \) detector pixels wide, where \( n_s \) is the number of subapertures in each dimension (i.e., there are \( n_s \times n_s \) subapertures in total). This means that a one-dimensional center-of-mass calculation for the line position in the direction orthogonal to the line will give the corresponding centroid location and wavefront gradient estimate in this direction for this subaperture, i.e., by measuring the offset of the line from the nominal origin position of each subaperture. Each subaperture is one pixel wide and a larger number (\( n_l \), e.g., eight) pixels long, depending on the field of view required. When the advanced processing techniques for line location are used [1], the number of pixels orthogonal to the cylindrical lenslet direction (\( n_l \)) can be reduced compared with a conventional SHS, while achieving the same field of view. These processing techniques effectively apply a continuity condition to the measured line position and greatly reduce the problem of subaperture cross talk, except for when the local wavefront tilt is great enough to place light from one subaperture on top of another.

Unless the detector has elongated pixels, it will be necessary to use nonsymmetrical reimaging optics to compress the image in one dimension, such that each subaperture is then one pixel wide and \( n_l \) pixels long (so that the wavefront gradient can be detected in

![Fig. 1. Conventional Shack–Hartmann wavefront sensor and a typical spot pattern with 64 subapertures (4096 detector pixels).](image1.png)

![Fig. 2. (a) Optically binned Shack–Hartmann wavefront sensor. The incoming wavefront is split using a beam splitter, and each beam then passes through orthogonal cylindrical lenslet arrays, to record the x and y wavefront gradients on separate detectors. (b) A typical resulting image from detector 1 (512 detector pixels, 8 \( \times \) 8 subapertures, vertical lenslet array). (c) A typical resulting image from detector 2 (512 detector pixels, 8 \( \times \) 8 subapertures, horizontal lenslet array). Elongated rectangular detector pixels have been used in (b) and (c) to make the image clearer.](image2.png)

![Fig. 3. Possible subdesigns for an optically binned Shack–Hartmann sensor, (a) using fold mirrors to rotate the reflected beam by 90° and (b) using shared cylindrical optics for each beam, one beam shown, to compress the phase in one dimension relative to the other.](image3.png)
This reimagining optics can consist of two cylindrical lenses as shown in Fig. 3(b).

A similar idea has previously been used for the Nasmyth Adaptive Optics for Multipurpose Instrumentation (NAOMI) instrument of the William Herschel Telescope (WHT) [2] and the Short Wave-length Adaptive Techniques (SWAT) adaptive optics (AO) system [3], using a conventional lenslet array and electronic binning in the detector (before readout), rather than optical binning. This will achieve a similar effect though will suffer from higher dark current and a lower readout rate than the OBSHS described here.

2. Practical Design of an Optically Binned Shack–Hartmann Sensor

When designing an OBSHS, the effect of misalignment between the two orthogonal sensor directions needs to be considered. To overcome this effect, a 90° beam rotation can be introduced to the reflected arm of the sensor, using two fold mirrors, the first of which directs light out of the beam splitter plane, and the second then directs light so that it is going in the same direction as the beam transmitted through the beam splitter. Two fold mirrors can also be used with transmitted beam so that both beams are then at the same height [see Fig. 3(a)], and if these fold by more than 90° back on themselves, the path length of the two beams can be equalized. Accurate alignment of these beams should be possible using standard techniques for mirror alignment. Both beams can then pass through the same cylindrical lenses and lenslet array and detected using the same detector, which greatly simplifies the system and improves stability. By using the same lenses and lenslet array for each beam, we can ensure that truly orthogonal wavefront gradients are measured. Figure 3 shows a possible design for the OBSHS. This design requires two cylindrical lenses to image the line pattern onto the detector, compressed in one dimension.

It is also possible to use a conventional lenslet array rather than a cylindrical (lenticular) array, if this is more readily available, though this will require additional optics. In this case, after the lenslet array, one conventional lens (to collimate the subapertures), the beam splitter, two cylindrical lenses (to compress in one dimension), and then a conventional lens (to image onto the detector) are required for each beam. The cylindrical lenses are used to compress the image in one dimension, so that the subaperture images in this dimension are only one pixel wide.

If a locally generated shuttered plane wave is included, injected at the beam splitter, this can be used as a subaperture tilt reference during calibration of the system, as proposed by Ref. [4]. By adding a calibrated tilt mirror to the reference path, both the orthogonality and absolute magnitude of the subaperture tilts can be calibrated. This allows fine tuning of the optical train and also provides an empirical basis set for reconstruction matrix generation, matched to the actual hardware.

A. Advantages of Optical Binning

There are several advantages for an OBSHS related to the reduced number of detector pixels required, in addition to those previously mentioned [1]. For example, if a conventional SHS uses 8 × 8 pixels per subaperture, the equivalent optically binned sensor will require eight pixels per subaperture for two orthogonal directions (16 pixels in total), or fewer if advanced line detection algorithms are used. This means that smaller detector arrays can be used, and frame rate can be correspondingly higher, reducing latency due to readout time in closed loop systems, which will improve the performance of these systems. Additionally, the use of fewer pixels means that detector read noise is reduced, and so the SNR can be increased. Computational and data bandwidth requirements are also reduced, an important consideration for next generation astronomical AO systems.

Systems that may have performance improved by using an OBSHS will have \( n_i > 2 \). This will include any open-loop WFS system, such as deformable mirror (DM) figure sensor detectors for multiobject adaptive optics (MOAO) applications: Open-loop control of deformable mirror elements by the AO loop means that precise knowledge of their figure at any given time is necessary and can be obtained using a figure sensor. In Subsection 3.E, we discuss the requirements for one particular figure sensor.

B. Disadvantages of Optical Binning

The light used in each orthogonal centroid calculation is halved by the beam splitter. In most situations this disadvantage is overcome by the reduction in detector readout noise due to the use of fewer detector pixels. However, for closed loop systems, this may not be the case. For such systems (once the loop has been closed), the wavefront can be assumed to be nearly flat within each subaperture, and so the Shack–Hartmann spot is close to the null position, and a small number of pixels (typically 2 × 2) can be used to estimate the centroid location. Signal and noise is therefore obtained from four pixels. In the optically binned case, half the light is used to estimate the centroid location for each orthogonal direction, and, likewise, half the pixels are used (two) for each direction, resulting in a lower SNR than in the conventional case. It should be noted that this is an extreme case, and most Shack–Hartmann sensors will use more pixels per subaperture even when the loop is closed, giving an advantage to the optically binned sensor. The OBSHS also uses extra optics compared with a conventional SHS, two fold mirrors, and possibly the two cylindrical lenses (most conventional systems will contain the same number of lenses for reimaging and scaling purposes). This therefore results in a slightly reduced throughput, though reflectivity of these mirrors can be very high.

3. Optically Binned Shack–Hartmann Sensor Performance

We compare the performance of an OBSHS with a conventional SHS using simple analytical consider-
ations, and Monte Carlo simulation of a closed loop astronomical AO system, the results of which are described here.

A. Analytical Performance Estimates

In general, the signal $s$ for the conventional SHS will be offset by the detector readout noise and photon shot noise scaling as $\sqrt{s + (N^2\sigma)^2}$, $N$ being the number of pixels in one dimension of each subaperture and $\sigma$ being the detector readout noise for a single pixel, giving a SNR of $s/\sqrt{s + (N^2\sigma)^2}$. For the OBSHS, the signal will be $s/2$, and the noise will scale as $\sqrt{s/2 + (N\sigma)^2}$, giving a SNR of $s/[2\sqrt{s/2 + (N\sigma)^2}]$. The optically binned case therefore gives better performance for $N > 2$ when detector readout noise is greater than about five electrons, for all light levels. When detector readout noise is one electron, the OBSHS gives better performance for $N > 5$ for all light levels, or $N > 2$ when $s < 40$ photons. For a noiseless detector, the OBSHS always gives worse SNR performance (by a factor of $1/\sqrt{2}$). For a low noise detector with $\sigma = 0.1$ electron [e.g., an electron multiplying CCD (EMCCD)], the OBSHS gives better SNR performance when $N > 6$ for $s > 20$, which will be the case in most practical situations.

It should be noted that two-dimensional weighted centroid calculations [5] that raise the detector signal from each pixel by a given power (typically 1.5) before spot centroid location determination cannot be used with the OBSHS since binning of the signal has already occurred. However, a similar one-dimensional weighting algorithm can be used.

B. Closed Loop Adaptive Optics Monte Carlo Simulation Comparisons

The performance of an OBSHS and a conventional SHS have been compared using the Durham AO simulation platform [6]. This software simulation comprises a classical AO system on a 42 m telescope for each WFS [one DM, one natural guide star (NGS), also the science target], and light for each WFS passes through the same atmospheric turbulence, as shown in Fig. 4. The atmospheric turbulence was simulated using the frozen turbulence model [7], with a ground layer, and layers at 200 m and 2 km (all uncorrelated, moving in different directions at different speeds). Except when otherwise stated, the wavefront sensor was assumed to have three electrons read noise, using a 13th magnitude guide star (5 ms integration time), $32 \times 32$ subapertures with 8 pixels per subaperture. The effect of feedback-loop latency was not investigated, though, since this will be reduced for the OBSHS (fewer pixels); the true performance of the OBSHS is likely to be further improved relative to a conventional SHS in closed loop situations. Further results of the simulation are not given here, as they would add length but not value to this paper, as only the relative performance of the two WFSs are of interest here.

C. Simulation Results

The effect on performance of several critical AO system parameters has been investigated, and the Strehl ratio of an image obtained using the AO corrected wavefront is used as a performance estimator (a perfectly flat wavefront gives a Strehl ratio of unity). The effect of guide star magnitude on the relative performance of the conventional SHS and the OBSHS was investigated, and results are shown in Fig. 5. It can be seen that the OBSHS offers better relative performance as the source grows fainter (at the lowest light level, the loop was not able to close in either case). This is predicted by the simple SNR calculations.

---

Fig. 4. Components of a Monte Carlo simulation used to compare wavefront sensor performance. A simulated beam splitter is used to direct half the light to a conventional AO and imaging system, while the other half is directed to an optically binned AO system. The performances of these systems can then be directly compared.

Fig. 5. Relative performance between a conventional and an optically binned SHS as a function of source magnitude. The inset shows the FWHM as a function of magnitude.
The effect of detector readout noise was also investigated, and Fig. 6 shows that for detectors with a nonzero readout noise, the OBSHS performance is better, due to there being fewer detector pixels required.

The effect on performance of the number of subapertures used is shown in Fig. 7, which shows that the OBSHS gives better performance than the conventional SHS. Higher order correction is given as the number of subapertures increases. However, light is then shared between more subapertures, and so image correction eventually becomes worse.

Similarly, as the number of pixels per subaperture is varied, the OBSHS gives better performance relative to the conventional SHS, as shown in Fig. 8. As the number of pixels increases, light is shared between more pixels, meaning that readout noise has a more dominant effect, resulting in poorer correction. When too few pixels are used, correction is also poor, as the AO loop is difficult to close.

D. Simulation Conclusions
The extensive but not exhaustive parameter space search carried out to compare the performance of a conventional SHS and OBSHS shows that the OBSHS can give better closed loop AO performance in most situations, in agreement with a simple consideration of signal and noise sources in the WFSs.

E. Case Study: DUGALL Figure Sensor
The Durham University generalized adaptive optics laser laboratory (DUGALL) is a proposed high-order on and off sky laser guide star (LGS) test facility. It will have several operational modes, including MOAO and laser tomographic adaptive optics (LTAO). MOAO involves open loop wavefront sensing and mirror shaping (the WFS does not view the DM), and relies on the shape of the unsensed deformable mirror being known at all times. Typically this could involve strain gauges [8] or direct measurement of the mirror shape, since hysteresis and nonlinearities within the mirror will mean that the shape of the mirror is not always equal to the initially requested shape. DUGALL proposes to use a 4 K actuator microelectromechanical systems (MEMS) deformable mirror, which does not contain strain gauges, and so direct measurement of the mirror shape is required using a figure sensor. Figure sensing must ideally operate at several times the rate of the AO loop, so that several adjustments to the mirror shape can be made during each AO loop iteration, until the desired shape is reached. The DUGALL AO loop will have a maximum operational rate of 1 kHz and so the figure sensor may require a frame rate of up to 10 kHz depending on the accuracy (time resolution) required and control algorithms used. Since the figure sensor measures the shape of a non-null (nonflat) mirror, wavefront gradients can be significant, and so a reasonable field of view is required for each subaperture, giving rise to a requirement of 8 × 8 pixels for a conventional SHS. The 4 K deformable mirror has 64 × 64 actuators, and so a SHS of this order is required. If a conventional SHS sensor is used, this would require a detector capable of reading a 512 × 512 array at 10 kHz and a platform for computing centroid locations in real time, requiring a data rate of 5 gigabytes/s, assuming two bytes per...
pixel. We are unaware of a suitable commercially available sensor able to meet these requirements.

By using an OBSHS, we would require two sensors each with $64 \times 512$ pixels, and a reduced data rate of about 500 megabytes/s for each sensor. There are several readily available commercial sensors that would meet this requirement. The reduced data rate makes centroid computation less demanding in real time, and the OBSHS will also give an improvement in SNR. We are currently developing such a WFS.

4. Conclusions

We have presented an improved design for a Shack–Hartmann WFS, using optical binning and a cylindrical lenslet array. This design promises to improve the SNR for wavefront reconstruction in most situations and involves splitting the wavefront for detection of the orthogonal wavefront gradients, using an optically binned SHS. We have presented general Monte Carlo simulation results that show that this OBSHS can lead to better performance than a conventional SHS, and we have presented schematic designs for such a detector. This WFS will be of particular interest for open loop systems where the wavefront gradients can be large, requiring many pixels per subaperture for detection, and for systems where a high frame rate and low latency is important.

References