DC characterization and 3D modelling of a triangular, epoxy-impregnated high temperature superconducting coil
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Abstract

The direct current (dc) characterization of high temperature superconducting (HTS) coils is important for applications, such as electric machines, superconducting magnetic energy storage and transformers. In this paper, the dc characterization of a triangular-shaped, epoxy-impregnated HTS coil wound with YBCO coated conductor intended for use in an axial-flux HTS motor is presented. Voltage was measured at several points along the coil to provide detailed information of its dc characteristics. The coil is modelled based on the $H$-formulation using a new three-dimensional (3D) technique that utilizes the real superconducting layer thickness, and this model allows simulation of the actual geometrical layout of the HTS coil structure. Detailed information on the critical current density’s dependence on the magnitude and orientation of the magnetic flux density, $J_c(B,\theta)$, determined from experimental measurement of a short sample of the coated conductor comprising the coil is included directly in the numerical model by a two-variable direct interpolation to avoid developing complicated equations for data fitting and greatly improve the computational speed. Issues related to meshing the finite elements of the real thickness 3D model are also discussed in detail. Based on a comparison of the measurement and simulation results, it is found that non-uniformity along the length exists in the coil, which implies imperfect superconducting properties in the coated conductor, and hence, coil. By evaluating the current–voltage ($I$–$V$) curves using the experimental data, and after taking into account a more practical $n$ value and critical current for the non-uniform region, the modelling results show good agreement with the experimental results, validating this model as an appropriate tool to estimate the dc $I$–$V$ relationship of a superconducting coil. This work provides a further step towards effective and efficient 3D modelling of superconducting devices for large-scale applications.

Keywords: high temperature superconductors, superconducting coil, superconducting tapes, 3D numerical analysis, dc characterization of coils

(Some figures may appear in colour only in the online journal)

1. Introduction

In recent years, long-length, high-quality high temperature superconducting (HTS) tapes have become commercially available, which increases the potential of practical, large-scale HTS applications. The direct current (dc) characterization of HTS coils is important for HTS applications, such as electric machines, superconducting magnetic energy storage...
and transformers. The dc properties can help determine the maximum allowable current in an HTS electric machine, which has a large impact on the size and weight of the machine, and hence, its power density [1–3]. We are investigating the design of an all-superconducting axial flux-type electric machine [4] and currently carrying out the dc characterization of HTS coils wound from YBCO coated conductors for the stator winding of the machine. A triangular-shaped HTS coil is one of the test candidates of this superconducting stator, which is commonly used, along with trapezoidal and circular designs, in conventional axial flux-type machines.

The analysis of the electromagnetic behaviour of superconducting materials based on the finite element method (FEM) can predict their performance for practical devices, such as HTS electrical machines [5–10], and assist in interpreting experiment results. There are three main formulations for FEM calculations: the $H$-formulation [11–14], the $A-V$ formulation [15–18] and the $T-\Omega$ formulation [19–21]. Maxwell’s equations can be written in each of these formulations and these formulations are equivalent in principle, but the solutions of the corresponding partial differential equations (PDEs) can be very different [22]. A more general overview of the potential and limits of numerical modelling for supporting the development of HTS devices is presented in [23].

A number of groups have reported research on the application of the $H$-formulation [3, 5, 6, 8–14, 24–34] and several authors have investigated the electromagnetic properties of HTS coils based on this method [3, 5, 6, 9, 10, 24, 30, 31, 34–36]. However, to our knowledge, there exists no three-dimensional (3D) HTS coil model using the $H$-formulation that utilizes the real superconducting layer thickness. A 3D model with the real superconducting layer thickness can analyse the electromagnetic behaviour of superconducting coils under complex geometries (i.e., those without a two-dimensional (2D) symmetric equivalent) and situations accurately. In addition, this technology can simulate HTS coated conductors with a magnetic substrate or other layers easily, which is applied in a similar way to the 2D method [26, 31].

In this paper, the dc characterization of a triangular-shaped HTS coil made from YBCO coated conductor for a prototype axial flux HTS electric machine is presented. Multiple voltage taps were used during measurement to provide detailed information on the dc characterization of the coil. A 3D coil model with the real superconducting layer thickness based on the $H$-formulation, implemented using the commercial FEM software package COMSOL Multiphysics 4.3a [37], is proposed to simulate the electromagnetic properties of the triangular coil.

In section 2, the experimental details are described, including detailed information on the critical current density’s dependence on the magnitude and orientation of the magnetic flux density, $J_c(B,\theta)$, determined from measurement of a short sample from the coated conductor comprising the coils. The $J_c(B,\theta)$ data is directly included in the numerical model by a two-variable direct interpolation to avoid developing complicated equations for data fitting. In section 3, the 3D FEM model framework is described and issues related to meshing the real thickness 3D model is discussed in details. In section 4, the experiment and simulation results are compared and it is found that inhomogeneities/non-uniformities along the length [38–40] exist in the tested coil. Based on the experimental data and modelling results, the inhomogeneous superconducting properties of the coated conductor are analysed in detail, highlighting the usefulness of such numerical techniques in interpreting experimental results.

### 2. Dc characterization and tape properties

The triangular, HTS pancake coil used in this study was wound using SuperPower SCS4050-AP coated conductor [41] and then impregnated in epoxy. A photograph of the coil is shown in figure 1. The total length of tape used was 18.6 m, resulting in 37 layers of silk ribbon interleave, vacuum impregnated with epoxy resin. The vacuum impregnation process included a 10 bar overpressure with nitrogen gas, which was maintained for 4–5 h before rotary baking. The resin used was stycast W19 with catalyst 11 in the ratio of 100:17. The specifications of the HTS coated conductor used [41] and the test coil are listed in table 1.

For the triangular coil shown in figure 1, the length of each side, measured from the centre of the corner bend at the outer turn, is 147 mm, and the distance between the top and bottom sides, measured from the inner turn, is 137 mm. The radius of the inner turn at each corner bend is 20 mm, which is larger than the minimum bend radius of the conductor (11 mm).

Ten voltage taps were utilized within the coil to help provide further detailed information for the dc characterization of the coil. By pairing the voltage taps, there are 13 voltage sections used for the measurements, as shown in figure 2. The voltages $V_1$–$V_9$ are the voltages between the

![Figure 1. The triangular, HTS pancake coil used in this study.](image)
Table 1. Specification of the coated conductor and triangular, HTS pancake coil.

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Triangular pancake coil</th>
</tr>
</thead>
<tbody>
<tr>
<td>Tape manufacturer</td>
<td>SuperPower</td>
</tr>
<tr>
<td>Tape type</td>
<td>SCS4050-AP</td>
</tr>
<tr>
<td>Tape critical current (self-field, 77 K)</td>
<td>94.7 A</td>
</tr>
<tr>
<td>Tape width, $w$</td>
<td>4 mm</td>
</tr>
<tr>
<td>Tape thickness, $d_c$</td>
<td>0.1 mm</td>
</tr>
<tr>
<td>YBCO layer thickness, $d_{sc}$</td>
<td>1 $\mu$m</td>
</tr>
<tr>
<td>Distance between YBCO layers</td>
<td>Approximately 220 $\mu$m</td>
</tr>
<tr>
<td>Length of conductor used</td>
<td>18.6 m</td>
</tr>
<tr>
<td>Coil turns, $n_c$</td>
<td>37</td>
</tr>
<tr>
<td>Coil side length</td>
<td>147 mm</td>
</tr>
<tr>
<td>Bend radius of coil corners</td>
<td>20 mm</td>
</tr>
</tbody>
</table>

Figure 2. The specific voltage taps and measured voltages for the triangular, HTS pancake coil.

individual taps, which are spaced approximately every 2 m along the tape length, except for the final voltage tap, which is located 1.4 m from its preceding tap. The first voltage tap is wired 1 m from the coil’s inner copper current contact and the final voltage tap is wired 0.2 m from the outer current contact to prevent an anomalous measurement due to localized heating of the tape near the coil terminals [34]. Hence, $V_1$ corresponds to the voltage across the innermost section of the coil and $V_6$ corresponds to the outermost section. $V_{10}$, $V_{11}$, and $V_{12}$ correspond to the voltages along each third of the coil, where $V_{10} = V_1 + V_2 + V_3$, $V_{11} = V_4 + V_5 + V_6$, and $V_{12} = V_7 + V_8 + V_9$, and $V_{13}$ is total coil voltage across a 17.4 m tape length.

The coil was cooled slowly to 77 K over several hours using liquid nitrogen vapour, followed by submersion in a liquid nitrogen bath. The current–voltage ($I$–$V$) curves of the coil and across the different voltage sections were recorded. The coil current was supplied by a dc power supply with a ramp-rate 0.5 A s$^{-1}$ to reduce the influence of the inductance of the coil. For the experimental measurement, as well as the numerical modelling, the critical current of the coil/voltage section is defined as the dc current when the electric field across a region reaches the characteristic electric field $E_0 = 1 \mu$V cm$^{-1}$ [42, 43]—this may be converted to a characteristic voltage using the distance between two taps. The dc measurements were repeated to confirm the reproducibility of the measurements and check for any thermal cycling effects, of which there was none.

Before winding the coil, the angular dependence $J_c(B, \theta)$ of the critical current, which is defined in figure 3, of a short sample from the spool of tape used to wind the coil was measured, the results of which are shown in figure 4. The magnitude of the applied field was varied from 0 to 0.7 T in 0.1 T increments.

In [44], the authors introduced an elliptical fitting function to represent the $J_c(B, \theta)$ relationship. In [40, 45], the authors developed a method to describe a more complex $J_c(B, \theta)$ relationship for coated conductors using 11 parameters with good agreement with experimental results. In [30], an alternative method was developed, based on measurements of the reduction in critical current due to parallel and perpendicular fields, using an angular function $G(\theta)$ for a particular applied field (100 mT in that paper). This also achieved good fitting of experiment data.

Here we propose a simpler method: a two-variable direct interpolation method, which completely avoids any complex data fitting process for $J_c(B, \theta)$ and expresses the anisotropic behaviour in the FEM software directly and accurately. The measured $J_c(B, \theta)$ data shown in figure 4 can be input directly as a single function, with two input variables, $B$ and $\theta$, and one output variable, $J_c$, automatically using a direct interpolation in COMSOL. This significantly simplifies the whole process whilst maintaining the highest possible accuracy for the input data. Symmetric behaviour is assumed for angles $90^\circ < \theta < 270^\circ$.

3. 3D numerical analysis framework

A finite element-based model based on 3D $H$-formulation is used to investigate the electromagnetic properties of the HTS coil. Considering the actual geometry of the test coil, the triangular coil needs to be modelled in 3D. 3D models of HTS materials have been developed by several groups using different formulations to carry out the numerical FEM
calculations [18, 21, 27, 32, 46–48]. The \( H \)-formulation is considered in this paper because models based on \( H \)-formulation can converge quickly and it is easy to impose electromagnetic boundary conditions related to the current flowing in the conductors [6] or to apply an external magnetic field, if required [49]. The introduction of the \( J_c(B, \theta) \) relationship is straightforward, too, since the magnetic field variable is available directly [23]. Furthermore, although 3D models of HTS materials based on \( H \)-formulation have been developed—for a single tape [27], bulk superconductors [27–29], two coupled tapes and helically-wound wires [32], Roebel cables [33], and coils using a direct [36] or homogenized [35] bulk approximation—there exists no 3D HTS coil model using both the \( H \)-formulation and the real superconducting layer thickness, which is developed here.

3.1. Governing equations

Similar to previous studies [27–29, 32, 33, 35, 36], the governing equations for the 3D \( H \)-formulation are derived from two of Maxwell’s equations: Faraday’s law (1) and Ampere’s law (2)

\[
\nabla \times \mathbf{E} + \frac{\partial \mathbf{B}}{\partial t} = \nabla \times \mathbf{H} + \frac{\partial (\mu_0 \mu_r \mathbf{H})}{\partial t} = 0, \\
\n\nabla \times \mathbf{H} = \mathbf{J},
\]

where \( \mathbf{H} = [H_x, H_y, H_z] \) represents the magnetic field components, \( \mathbf{J} = [J_x, J_y, J_z] \) represents the current density and \( \mathbf{E} = [E_x, E_y, E_z] \) represents the electric field components. \( \mu_0 \) is the permeability of free space. For the superconducting layers and air subdomains, the relative permeability \( \mu_r = 1 \).

It is assumed that the electric field \( \mathbf{E} \) is parallel to the current density \( \mathbf{J} \) [3, 27–36] and the electrical properties of the superconductor are modelled by the \( E-J \) power law [50, 51] given in (3)

\[
\mathbf{E} = \frac{E_0}{J_c(B, \theta)} \left| \begin{array}{c}
J_x \\
J_y \\
J_z
\end{array} \right|^{n-1} \mathbf{J}
\]

where \( E_0 \) is the characteristic electric field 1 \( \mu \text{V cm}^{-1} \) as described in section 2. For HTS materials, \( n \) is usually within the range of 5 (strong flux creep) and 50 (limiting value for HTS and LTS materials) [6, 17, 50]. When \( n > 20 \), it becomes a good approximation of Bean’s critical state model [46]. Therefore, in this paper, we assume \( n = 21 \).

The knowledge of the in-field critical current density behaviour, \( J_c(B, \theta) \), of the coated conductor used to wind the coil is input as a two-variable direct interpolation of the experimental data (figure 4) into COMSOL, where \( B \) is the magnitude of the local magnetic flux density and \( \theta \) is the angle with respect to the top surface of the tape (figure 3). In order to derive these two parameters, \( B_\perp \) and \( B_\parallel \), which represent the perpendicular and parallel components of the flux density, respectively, can be expressed depending on the specific geometrical structure, where \( B = \sqrt{B_\perp^2 + B_\parallel^2} \) and \( \theta = \arctan(B_\perp/B_\parallel) \). For non-superconducting subdomains (e.g., the air between the tapes and surrounding the coil), a linear

Figure 5. 1/6th of the length of the coil is modelled using symmetric boundary conditions.

Ohm’s law is considered, \( \mathbf{E} = \rho \mathbf{J} \), where \( \rho \) is the specific, constant resistivity for the material.

3.2. Geometry, boundary conditions and current constraints

Considering the high mesh density and computation time required for a full 3D model, geometric symmetry is made use of, as shown in figure 5: only 1/6th of the length of the coil is modelled using symmetric boundary conditions.

In this paper, since only the transport current problem is addressed and no external magnetic field is applied, Dirichlet boundary conditions [6, 29, 33] are applied such that \( H_x = H_y = H_z = 0 \), for a sufficiently large air subdomain. Neumann boundary conditions are applied to describe the magnetic field continuity between the air and superconductor subdomains. Finally, integral constraints are applied to the superconducting layers to represent the particular transport current flowing in the coil. A transport current \( I_t \) through any surface \( s \) can be described as follows:

\[
I_t = \int \mathbf{J} \cdot \mathbf{S}_t \, ds, \quad (4)
\]

where \( \mathbf{S}_t \) represents the local unit vector tangential to the cross-section of the superconducting layer.

3.3. Mesh considerations

The mesh is a key factor for finite element analysis and the selection of an appropriate mesh method is crucial for accurate and fast simulations. For the real thickness 3D coil model, it is found that the combinations of different mesh methods can decrease the number of mesh element and degrees of freedom effectively, whilst maintaining good accuracy and convergence during the simulation.

Mesh scaling and mapped meshing are both good methods to improve the convergence speed and reduce the simulation time required. A mapped mesh [6] is applied in the 2D cross-section of the HTS coated conductor, as shown in figure 6, to decrease the number of mesh elements. For clarity, there are only four turns of the coil shown and only half of each conductor because of geometric symmetry. Mesh scaling is another effective method to reduce the number of created elements, which scales the geometry along the thin direction before meshing and then scales the mesh back to fit the mesh in the original geometry. This is applied to the cross-section of the air subdomain between the superconducting tapes. A mapped mesh can be also applied to the air subdomain between the superconducting tapes [6]; however, the
reason that mesh scaling is recommended in the region of air domain between the HTS tapes is that mesh scaling in that region of the coil model improves convergence and speed at least one order of magnitude over a mapped mesh, without reduction in accuracy. Therefore, such a combined mapped-scaled mesh is a good method for improving convergence speed to allow 3D model to be simulated with real thickness superconducting layer.

A swept mesh [32] is applied to allow the real thickness of the superconducting tape to be modelled, which starts from 2D cross-section of the 3D HTS coil and sweeps along the length of each turn in the coil. By investigation, some mesh elements are inverted at the bent part of the HTS coil, which causes the swept mesh to fail, so the remaining regions are split into regions A and B by a large rectangular boundary (also shown in figure 6), which eliminates such inverted mesh elements.

### 3.4. Simulating the dc properties

When simulating the 3D HTS coil model, the applied current was ramped at a ramp rate of 7 A s\(^{-1}\). Initially, uniform \(J_c(B, \theta)\) properties were assumed along the tape of the coil to calculate the expected current–voltage (I–V) characteristic of the coil. To derive the I–V characteristic for each of the different voltage sections \((V_{11}–V_{13})\) of the coil, the voltage from the integration of local electric field is required.

The average electric field and voltage for \(V_{11}–V_{13}\) in the 3D triangular model are shown in (5) and (6), respectively.

\[
E_{\text{ave},i}(i = 1\ldots13) = \frac{\sum_m E_{\text{norm}} dv}{\sum_m dv}, \quad (5)
\]

\[
V_i(i = 1\ldots13) = E_{\text{ave},i} l_i, \quad (6)
\]

where \(i\) denotes voltage sections 1–13 in figure 2, and \(m\) denotes the turn number in each section (3 to 37 turns in the triangular coil, corresponding to the positions of the voltage taps). \(E_{\text{norm}} = \sqrt{E_x^2 + E_y^2 + E_z^2}\) represents the local electric field in the triangular coil. \(v\) represents the volume of each turn \(m\) and the term \(\sum_m dv\) is the volume sum of these \(m\) turns. \(l_i\) represents the wire length of each voltage section. Taking voltage section 1 as an example, \(m\) varies from 3 to 6.

### 4. Results and discussion

The predicted I–V curve from the numerical analysis and the dc measurement results for the triangular coil are shown in figure 7. \(V_{13}\) is the total coil voltage, as shown in figure 2.

Based on figure 7, the experimental result indicates a critical current for the coil of around 38 A, and the simulation result, based on the previous assumptions, estimates a critical current of around 63 A, indicating a large discrepancy between the two. The simulated curve is based on the measured \(J_c(B, \theta)\) behaviour of a short sample and assumes uniform properties along length of conductor in the coil. Here, we investigate the uniformity of the coil in more detail using the experimentally measured results.

The measured I–V curves for \(V_{10}–V_{13}\) are shown in figure 8, where \(V_{10}, V_{11}\) and \(V_{12}\) are the I–V curves for each third of the coil. In addition, the measured, average electric field for voltage sections \(V_1–V_9\) when the input current reaches the critical current of the triangular coil, and the test data for the critical current every 5 m along the conductor (provided by the manufacturer) are shown in figure 9.
Based on figures 8, 9(a) and (b), non-uniformity of the critical current exists along the length of the HTS triangular coil. Based on figure 9(a), the maximum electric field, corresponding to the region of lowest critical current in the coil, exists between 5 and 7 m (voltage $V_3$ in the triangular coil). Based on figure 9(b), there are regions of comparatively lower critical current between 4 and 14 m, indicating overlap between the maximum electric field and lower critical current.

The previous assumption of uniform critical current density along the length of tape is unreasonable due to the presence of this non-uniformity along its length. If one were to assume uniform properties, it is expected that the inner turn at the bends/corners will see a relatively higher localized magnetic field, which would determine the overall critical current of the coil [31, 49].

It is a common phenomenon that some non-uniformity exists along the length of an HTS coated conductor [2, 38–40, 52–61]. Non-uniformity along the length [38–40, 54] can be a crucial concern in HTS coils and the performance of the coated conductor can be influenced by many factors, such as the processing of the material [38, 39, 52–55, 58] or winding of the coil [2, 56, 57, 59–61]. In terms of material processing [38, 39, 52–55, 58], the percentage of doping in the HTS tape, the deposition rate, and the roughness of the surface of the tape can have a significant impact on the uniformity over long lengths. From data along long lengths from manufacturers and research institutions [38, 39, 52–55, 58], it can be seen that the critical current in self-field along the length can vary, sometimes suddenly in particular, localized sections. If the angular dependence of critical current density for a specific magnetic field is also considered, the difference may become more obvious and one such case can be seen in [38].

In terms of winding the coil [2, 56, 57, 59–61], the HTS tape is sensitive to bending strain, which can lead to a decrease in the critical current of the coil. The specific reason for the non-uniformity along the length in this particular case is beyond the scope of our investigations, but utmost care was taken during the winding process to avoid excessive strain.

Based on figure 9(a), there is a significant electric field generated only in voltage section $V_3$ of the coil, which also dominates the voltage of the whole coil. For the other regions of the triangular coil, there are comparatively lower electric fields. Following [59], an approximation of uniform $J_c(B, \theta)$ can be made within each section, whether non-uniform (section $V_3$) or uniform (all other voltage sections). Using the experimental results for the non-uniform region, as shown in figure 10, a more realistic $J_c(B, \theta)$ and $n$ value can be calculated for this particular region.

Following [59], the critical current of this region is 14 A and the $n$ value cannot be considered constant. When the current is over 14 A, $n = 1.98$ and below 14 A, $n = 3.63$.

In order to estimate the critical current of the tape in $V_3$ based on information in figure 4, the average magnetic field magnitude and orientation in this region are needed. To derive the average magnetic field magnitude and its orientation in voltage sections, the integration of local magnetic field magnitude and orientation is needed. The average magnetic field magnitude and its orientation for $V_1$–$V_3$ in the 3D model are shown in equations (7) and (8), respectively.

$$B_{\text{ave},i}(i = 1 \sim 13) = \frac{\sum_m B_i dV}{\sum_m dV}, \quad (7)$$

$$\theta_{\text{average},i} = \frac{\sum_m \theta_i dV}{\sum_m dV}, \quad (8)$$
Table 2. $n$ value and critical current density of the triangular pancake coils.

<table>
<thead>
<tr>
<th>Regions</th>
<th>$n$ value</th>
<th>Critical current density</th>
</tr>
</thead>
<tbody>
<tr>
<td>Non-uniform $V_3$</td>
<td>3.63 ($I&lt;14$ A) 1.98 ($I&gt;14$ A)</td>
<td>$\frac{14}{33} J_c(B, \theta)$</td>
</tr>
<tr>
<td>Other uniform regions ($V_1$, $V_2$, $V_6-V_9$)</td>
<td>21</td>
<td>$J_c(B, \theta)$</td>
</tr>
</tbody>
</table>

where $i$ denotes voltage section 1–13 in figure 2, and $m$ denotes turn number in each section (3 to 37 turns in the triangular coil, corresponding to the positions of the voltage taps). $B$ and $\theta$ represent the local flux density magnitude and its orientation, respectively. As per equation (5), $v$ represents the volume of turn $m$.

Based on the previous ideal coil model (with the approximation of uniform critical current along the entire length of the tape in the whole winding) and equations (7), (8), the average magnetic field $B = 0.014$ T and angle $\theta = 6^\circ$ in $V_3$ when the applied current is 14 A. Considering the $J_c(B, \theta)$ data presented in figure 4, the critical current of the tape in that region is $I_c(0.014$ T, $6^\circ) = 93$ A. Here, the same $J_c(B, \theta)$ behaviour is assumed, but the magnitude of $J_c(B, \theta)$ is assumed to decrease in proportion. Therefore, the new critical current density in the non-uniform region is fixed to $J_c(B, \theta) \times 14/93$ with the previous critical current density for all other (uniform) regions, as shown in table 2. Using this information, the new simulated $I-V$ curves are compared with the experimental measurements using the average electric field [34, 40] and the results are shown in figure 11.

From figure 11, it can be seen that experiment results are now almost consistent with the simulation results, when taking into account the non-uniform $V_3$ region in the coil, resulting in a large voltage generated in this region, which impacts significantly on the overall coil voltage and hence critical current. $V_3$ represents the non-uniform region and $V_1-V_3$ represents the uniform regions. From figure 11, it can be seen that 3D HTS model can simulate both uniform and non-uniform regions and the results match well with the experimental results. The consistence of the modelling and experimental results demonstrates this 3D model as an effective tool to estimate current–voltage relationship of a superconducting coil, especially for those without a 2D symmetric equivalent, such as racetrack and triangular coils.

At the same time, the 3D finite element model can also express field distribution and current density distribution accurately and it makes a valuable tool for coil optimization. It can be even extended as part of superconducting machine, which cannot be simply simulated by 2D models, and provides a further step towards effective and efficient 3D modelling of large-scale HTS applications.

5. Conclusion

In this paper, the dc properties of a triangular, epoxy-impregnated HTS coil made from YBCO coated conductor for a prototype axial flux HTS electric machine were measured. Multiple voltage taps were utilized within the coil during measurement to help provide further detailed information on the dc characterization of the coil.

A 3D numerical model, based on the $H$-formulation and including the real superconducting layer thickness, is implemented using the commercial FEM software package COMSOL Multiphysics 4.3a to simulate the electromagnetic properties of the coil. Detailed information on the critical current density’s dependence on the magnitude and orientation of the magnetic flux density, $J_c(B, \theta)$, determined from experimental measurement of a short sample of the coated conductor comprising the coil is included directly in the numerical model by a two-variable direct interpolation to avoid developing complicated equations for data fitting and greatly improve the computational speed. In addition, a combined mapped-scaled mesh is proposed for improving the model’s convergence to allow a fast and efficient 3D simulation including the real thickness of the superconducting layer.

Numerical analysis can help us understand the experiment result, and based on the comparison of measurement and simulation results, it is found that non-uniformity along the length exists in the coil. By evaluating the current–voltage ($I-V$) curves using experimental data, a decreased $n$ value and critical current is observed in a non-uniform region of the coil. When the 3D model is modified to account for this practical critical current and $n$ value, the experiment and modelling results show good agreement, validating this 3D model as an effective tool to estimate dc $I-V$ relationship of a superconducting coil. At the same time, this model allows the development of an effective and efficient 3D model for analysing large-scale HTS applications.

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